1. Solution:

The proof is

$$\begin{split} [AB,C]_{\mathrm{PB}} &= \sum_{i} \left(\frac{\partial AB}{\partial q_{i}} \frac{\partial C}{\partial p_{i}} - \frac{\partial C}{\partial q_{i}} \frac{\partial AB}{\partial p_{i}} \right) \\ &= \sum_{i} \left[\left(\frac{\partial A}{\partial q_{i}} B + \frac{\partial B}{\partial q_{i}} A \right) \frac{\partial C}{\partial p_{i}} - \frac{\partial C}{\partial q_{i}} \left(\frac{\partial A}{\partial p_{i}} B + \frac{\partial B}{\partial p_{i}} A \right) \right] \\ &= \sum_{i} \left(A \frac{\partial B}{\partial q_{i}} \frac{\partial C}{\partial p_{i}} - A \frac{\partial C}{\partial q_{i}} \frac{\partial B}{\partial p_{i}} + B \frac{\partial A}{\partial q_{i}} \frac{\partial C}{\partial p_{i}} - B \frac{\partial C}{\partial q_{i}} \frac{\partial A}{\partial p_{i}} \right) \\ &= A \sum_{i} \left(\frac{\partial B}{\partial q_{i}} \frac{\partial C}{\partial p_{i}} - \frac{\partial C}{\partial q_{i}} \frac{\partial B}{\partial p_{i}} \right) + B \sum_{i} \left(\frac{\partial A}{\partial q_{i}} \frac{\partial C}{\partial p_{i}} - \frac{\partial C}{\partial q_{i}} \frac{\partial A}{\partial p_{i}} \right) \\ &= A [B, C]_{\mathrm{PB}} + [A, C]_{\mathrm{PB}} B. \end{split}$$

2. Solution:

 $\mathbf{a})$

If the Hamiltonian does not explicitly depend on time i.e.

$$\frac{\partial H}{\partial t} = 0,$$

then it holds

$$\frac{\mathrm{d}H}{\mathrm{d}t} = -[H, H]_{\mathrm{PB}} + \underbrace{\frac{\partial H}{\partial t}}_{=0} = \sum_{i} \left(\frac{\partial H}{\partial q_{i}} \frac{\partial H}{\partial p_{i}} - \frac{\partial H}{\partial q_{i}} \frac{\partial H}{\partial p_{i}} \right) = 0.$$

b)

If the Hamiltonian has a property

$$\frac{\partial H}{\partial q_k} = 0,$$

then it holds that

$$\begin{split} \frac{\mathrm{d}p_k}{\mathrm{d}t} &= -[H, p_k]_{\mathrm{PB}} + \underbrace{\frac{\partial p_k}{\partial t}}_{=0} \\ &= -\sum_i \left(\underbrace{\frac{\partial H}{\partial q_i}}_{=\delta_{ki}} \underbrace{\frac{\partial p_k}{\partial p_i}}_{=0} - \underbrace{\frac{\partial P_k}{\partial q_i}}_{=0} \underbrace{\frac{\partial H}{\partial p_i}}_{=0} \right) \\ &= -\sum_i \delta_{ik} \frac{\partial H}{\partial q_i} \\ &= -\underbrace{\frac{\partial H}{\partial q_k}}_{=0} \\ &= 0. \end{split}$$

3. Solution:

Our statement is

$$[L_i, L_j]_{PB} = \sum_k \epsilon_{ijk}.$$

If i = j, then $[L_i, L_i]_{PB} = 0$ and $\epsilon_{iik} = 0$ because

$$\epsilon_{ijk} = -\epsilon_{jik} \Rightarrow \epsilon_{iik} = -\epsilon_{iik} \Rightarrow \epsilon_{iik} = 0.$$

Hence the statement holds. Furthermore, the statement is correct if we change the indices $(i,j) \to (j,i)$, because $[L_i, L_i]_{PB} = -[L_j, L_i]_{PB}$ and $\epsilon_{ijk} = -\epsilon_{jik}$. Thus we have left only three cases to prove: (1,2), (1,3) and (2,3). We recall

$$\mathbf{L} = \mathbf{r} \times \mathbf{p} = (yp_z - zp_y)\mathbf{i} + (zp_x - xp_z)\mathbf{j} + (xp_y - yp_x)\mathbf{k} = L_1\mathbf{i} + L_2\mathbf{j} + L_3\mathbf{k}.$$
If $(i, j) = (1, 2)$, then

$$[L_{1}, L_{2}]_{PB} = \sum_{i} \left[\frac{\partial}{\partial q_{i}} (yp_{z} - zp_{y}) \frac{\partial}{\partial p_{i}} (zp_{x} - xp_{z}) - \frac{\partial}{\partial q_{i}} (zp_{x} - xp_{z}) \frac{\partial}{\partial p_{i}} (yp_{z} - zp_{y}) \right]$$

$$= \sum_{i} \left[(\delta_{i2}p_{z} - \delta_{i3}p_{y}) (z\delta_{i1} - x\delta_{i3}) - (\delta_{i3}p_{x} - \delta_{i1}p_{z}) (y\delta_{i3} - z\delta_{i2}) \right]$$

$$= \sum_{i} \left[\delta_{i3}^{2}p_{y}x - \delta_{i3}^{2}p_{x}y \right]$$

$$= xp_{y} - yp_{x}$$

$$= L_{3}$$

(note that terms e.g. $\delta_{i1}\delta_{i2}$, $\delta_{i1}\delta_{i3}$... sum up to zero) and the permutation symbol gives

$$\sum_{k} \epsilon_{12k} = \underbrace{\epsilon_{121}}_{=0} L_1 + \underbrace{\epsilon_{122}}_{=0} L_2 + \underbrace{\epsilon_{123}}_{=1} L_3 = L_3.$$

Others in a similar way:

$$[L_{1}, L_{3}]_{PB} = \sum_{i} \left[\frac{\partial}{\partial q_{i}} (yp_{z} - zp_{y}) \frac{\partial}{\partial p_{i}} (xp_{y} - yp_{x}) - \frac{\partial}{\partial q_{i}} (xp_{y} - yp_{x}) \frac{\partial}{\partial p_{i}} (yp_{z} - zp_{y}) \right]$$

$$= \sum_{i} \left[(\delta_{i2}p_{z} - \delta_{i3}p_{y}) (x\delta_{i2} - y\delta_{i1}) - (\delta_{i1}p_{y} - \delta_{i2}p_{x}) (y\delta_{i3} - z\delta_{i2}) \right]$$

$$= \sum_{i} \left[\delta_{i2}^{2}p_{z}x - \delta_{i2}^{2}p_{x}z \right]$$

$$= xp_{z} - zp_{x}$$

$$= -L_{2}$$

and

$$\sum_{k} \epsilon_{13k} = \underbrace{\epsilon_{131}}_{=0} L_1 + \underbrace{\epsilon_{132}}_{=-1} L_2 + \underbrace{\epsilon_{133}}_{=0} L_3 = -L_2$$

and the last case

$$[L_{2}, L_{3}]_{PB} = \sum_{i} \left[\frac{\partial}{\partial q_{i}} (zp_{x} - xp_{z}) \frac{\partial}{\partial p_{i}} (xp_{y} - yp_{x}) - \frac{\partial}{\partial q_{i}} (xp_{y} - yp_{x}) \frac{\partial}{\partial p_{i}} (zp_{x} - xp_{z}) \right]$$

$$= \sum_{i} \left[(\delta_{i3}p_{x} - \delta_{i1}p_{x}) (x\delta_{i2} - y\delta_{i1}) - (\delta_{i1}p_{y} - \delta_{i2}p_{x}) (z\delta_{i1} - x\delta_{i3}) \right]$$

$$= \sum_{i} \left[\delta_{i1}^{2}p_{z}y - \delta_{i1}^{2}p_{y}z \right]$$

$$= yp_{z} - zp_{y}$$

$$= L_{1}$$

and

$$\sum_{k} \epsilon_{23k} = \underbrace{\epsilon_{231}}_{=1} L_1 + \underbrace{\epsilon_{232}}_{=0} L_2 + \underbrace{\epsilon_{233}}_{=0} L_3 = L_1.$$

Now we see that the statement holds for every index. Because

$$L^2 = \sum_{j} L_j^2,$$

direct calculation gives us

$$[L^{2}, L_{i}]_{PB} = \sum_{j} [L_{j}^{2}, L_{i}]_{PB}$$

$$= \sum_{j} \left(L_{j} [L_{j}, L_{i}]_{PB} + [L_{j}, L_{i}]_{PB} L_{j} \right)$$

$$= 2 \sum_{j} L_{j} [L_{j}, L_{i}]_{PB}$$

$$= 2 \sum_{j} L_{j} \sum_{k} \epsilon_{jik} L_{k}$$

$$= 2 \sum_{jk} \epsilon_{jik} L_{j} L_{k}$$

$$= 0.$$

where we noticed

$$\sum_{jk} \epsilon_{jik} L_j L_k = -\sum_{jk} \epsilon_{kij} L_k L_j = -\sum_{kj} \epsilon_{jik} L_j L_k = (*) - \sum_{jk} \epsilon_{jik} L_j L_k$$

$$\Rightarrow \sum_{jk} \epsilon_{jik} L_j L_k = 0.$$

In the step (*) we renamed the indices $(j,k) \to (k,j)$. If we consider a group of particles (N particles) that has coordinates $q_i^{(a)}$ and momenta $p_i^{(a)}$ with indices $a=1,\ldots,N$ and i=1,2,3, we have

$$\mathbf{L} = \sum_{a=1}^{N} \mathbf{L}^{(a)},$$

where

$$\mathbf{L}^{(a)} = \mathbf{r}^{(a)} \times \mathbf{p}^{(a)}.$$

Now we calculate

$$\begin{split} [L_{i}^{(a)},L_{j}^{(b)}]_{\text{PB}} &= \sum_{c=1}^{N} \sum_{k=1}^{3} \left(\frac{\partial L_{i}^{(a)}}{\partial q_{k}^{(c)}} \frac{\partial L_{j}^{(b)}}{\partial p_{k}^{(c)}} - \frac{\partial L_{j}^{(b)}}{\partial q_{k}^{(c)}} \frac{\partial L_{i}^{(a)}}{\partial p_{k}^{(c)}} \right) \\ &= \sum_{c} \sum_{k} \left(\delta_{ac} \frac{\partial L_{i}^{(a)}}{\partial q_{k}^{(a)}} \delta_{bc} \frac{\partial L_{j}^{(b)}}{\partial p_{k}^{(b)}} - \delta_{bc} \frac{\partial L_{j}^{(b)}}{\partial q_{k}^{(b)}} \delta_{ac} \frac{\partial L_{i}^{(a)}}{\partial p_{k}^{(a)}} \right) \\ &= \underbrace{\left(\sum_{c} \delta_{ac} \delta_{bc} \right)}_{=\delta_{ab}} \underbrace{\sum_{k} \left(\frac{\partial L_{i}^{(a)}}{\partial q_{k}^{(a)}} \frac{\partial L_{j}^{(b)}}{\partial p_{k}^{(b)}} - \frac{\partial L_{j}^{(b)}}{\partial q_{k}^{(b)}} \frac{\partial L_{i}^{(a)}}{\partial p_{k}^{(a)}} \right)}_{=[L_{i}^{(a)}, L_{j}^{(b)}]_{\text{PB}}} \\ &= \delta_{ab} [L_{i}^{(a)}, L_{j}^{(b)}]_{\text{PB}}.(*) \end{split}$$

Because $\mathbf{L}^{(a)}$ only depend on $q_i^{(a)}$ and $p_i^{(a)}$ but not on $q_i^{(b)}$ or $p_i^{(b)}$ $(a \neq b)$, it should be

$$[L_i^{(a)}, L_j^{(b)}]_{PB} = 0 \quad a \neq b.$$

The above calculation proves this and is the reason why the manyparticle problem reduces to the single particle case:

$$[L_{i}, L_{j}]_{PB} = \left[\sum_{a} L_{i}^{(a)}, \sum_{b} L_{j}^{(b)}\right]_{PB}$$

$$= \sum_{ab} \underbrace{[L_{i}^{(a)}, L_{j}^{(b)}]_{PB}}_{=\delta_{ab}[L_{i}^{(a)}, L_{j}^{(b)}]_{PB}}$$

$$= \sum_{ab} \delta_{ab}[L_{i}^{(a)}, L_{j}^{(b)}]_{PB}$$

$$= \sum_{a} \underbrace{[L_{i}^{(a)}, L_{j}^{(a)}]_{PB}}_{=\sum_{k} \epsilon_{ijk} L_{k}^{(a)}}$$

$$= \sum_{a} \sum_{k} \epsilon_{ijk} L_{k}^{(a)}$$

$$= \sum_{k} \epsilon_{ijk} \underbrace{(\sum_{a} L_{k}^{(a)})}_{=L_{k}}$$

$$= \sum_{k} \epsilon_{ijk} L_{k}.$$

Because we already proved $[L^2, L_i]_{PB}$ for a single particle only using the result $[L_i, L_j]_{PB} = \sum_k \epsilon_{ijk} L_k$, we can prove the same result to a many-particle case reducing the Poisson brackets to a single particle case using the formula (*) and using result $[L_i, L_j]_{PB} = \sum_k \epsilon_{ijk} L_k$.

4. Solution:

The Lagrangian is

$$L = T = \frac{1}{2}m\dot{x}^2$$

meaning that canonical momentum is

$$p = \frac{\partial L}{\partial \dot{x}} = m\dot{x}$$

and thus the Hamiltonian has a form

$$H(x,p) = p\dot{x} - L = m\dot{x}^2 - \frac{1}{2}m\dot{x}^2 = \frac{1}{2}m\dot{x}^2 = \frac{p^2}{2m}.$$

The Hamilton equations say that

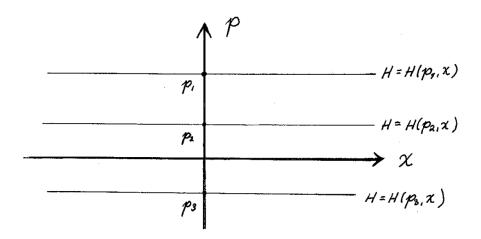
$$\dot{x} = \frac{\partial H}{\partial p} \Rightarrow \dot{x} = \frac{p}{m}$$
$$\dot{p} = -\frac{\partial H}{\partial x} \Rightarrow \dot{p} = 0$$

and the solution for these equations is

$$p(t) = p(0)$$

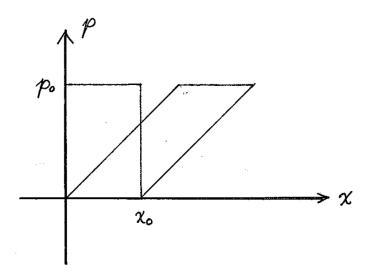
 $x(t) = \frac{p(0)}{m}t + x(0).$

Because L does not explicitly depend on time, the Hamiltonian is a constant of motion and that is the reason why the solutions of the Hamilton equations are contours for the Hamiltonian. Because the Hamiltonian just depends on the momentum, the contours of the Hamiltonian are parallel to the x-axis.



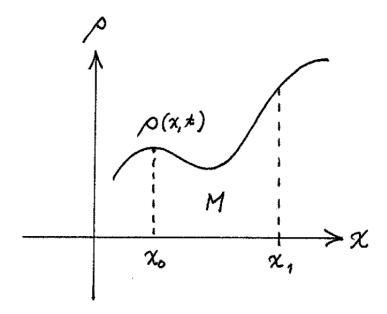
The solution says that a point is moving with speed proportional to the initial value of momentum along the line p = p(0). This implies that

the points in the base of the rectangle (p=0) are staying still and the points in the top are moving along x-axis with constant speed p(0)/m. It is easy to see that the initial rectangle changes to a parallelogram when time goes on. With a short calculation using the solution, we can notice that the area A is the same in the rectangle as in the parallelogram. The conservation of the area means that also density is constant and thus Liouville's theorem holds.



5. Solution:

We can consider an arbitrary distribution $\rho(x,t)$. Let's denote an arbitrary interval with $I = [x_0, x_1]$ that does not depend on time. The mass



M inside the interval I is

$$M = \int_{I} \rho(x, t) \mathrm{d}x.$$

The change of mass with time is

$$\frac{\mathrm{d}M}{\mathrm{d}t} = \frac{\mathrm{d}}{\mathrm{d}t} \int_{I} \rho(x,t) \mathrm{d}x = \int_{I} \frac{\partial \rho}{\partial t}(x,t) \mathrm{d}x.$$

On the other hand, there is mass flow going in and coming out in the ending points of the interval. In the point x the mass flux to the positive x-direction is

$$\rho(x,t)v(x,t)$$
.

Now we deduce that the mass change is the same as the net flux:

$$\frac{\mathrm{d}M}{\mathrm{d}t} = \rho(x_0, t)v(x_0, t) - \rho(x_1, t)v(x_1, t)$$

$$= -\int_{x_0}^{x_1} \rho(x, t)v(x, t)$$

$$= -\int_{x_0}^{x_1} \frac{\mathrm{d}}{\mathrm{d}x} [\rho(x, t)v(x, t)] \mathrm{d}x.$$

Because our two representations for the mass change have to be same, we have a relation

$$\int_{I} \frac{\partial \rho}{\partial t}(x,t) dx = -\int_{I} \frac{d}{dx} [\rho(x,t)v(x,t)] dx$$

$$\Leftrightarrow$$

$$\int_{I} \left\{ \frac{\partial \rho}{\partial t}(x,t) + \frac{d}{dx} [\rho(x,t)v(x,t)] \right\} = 0$$

Because our interval I is arbitrary, the integrand must always be zero i.e.

$$\begin{split} &\frac{\partial \rho}{\partial t}(x,t) + \frac{\mathrm{d}}{\mathrm{d}x}[\rho(x,t)v(x,t)] = 0 \\ &\Leftrightarrow \\ &\frac{\partial \rho}{\partial t}(x,t) + v(x,t)\frac{\mathrm{d}\rho}{\mathrm{d}x}(x,t) + \rho(x,t)\frac{\mathrm{d}v}{\mathrm{d}x}(x,t) = 0 \\ &\Leftrightarrow \\ &\frac{\partial \rho}{\partial t}(x,t) + v(x,t)\frac{\mathrm{d}\rho}{\mathrm{d}x}(x,t) = -\rho(x,t)\frac{\mathrm{d}v}{\mathrm{d}x}(x,t). \end{split}$$